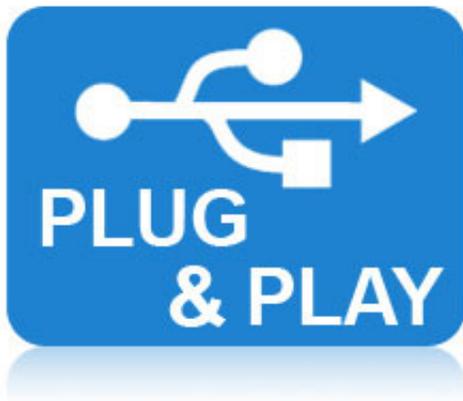


# Quick Start Guide

## Installation on 8, 8.1, 10 and 11

Airspy is a plug-and-play device and does not require any particular driver installation on Windows download and install the right driver for you.



There are exceptions where the original configuration of the PC does not allow the automatic installation (/download) should be installed manually with the following procedure:

- Download and unzip the WinUSB Compatibility Driver (/download)
- Open the device manager and select Airspy
- Select "Update Driver" then "Browse My Computer" to the inf file

## Installation on Windows Server or Windows X

Please don't. They are not supported.

# Using SDR#

Airspy was designed by the same people who developed the SDR# software (<http://sdrsharp.com>) : its powerful features.

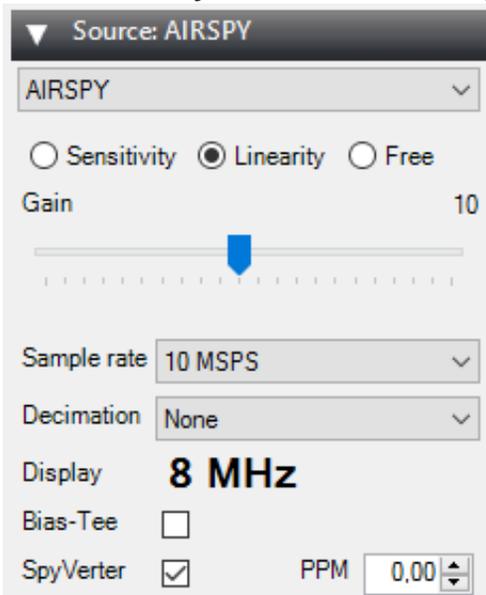
First, go to the download page (/download) and get a copy. Then run SDRSharp.exe and select the ‘



Then next step is the gain configuration. As depicted in this screen shot, there are many gain mode

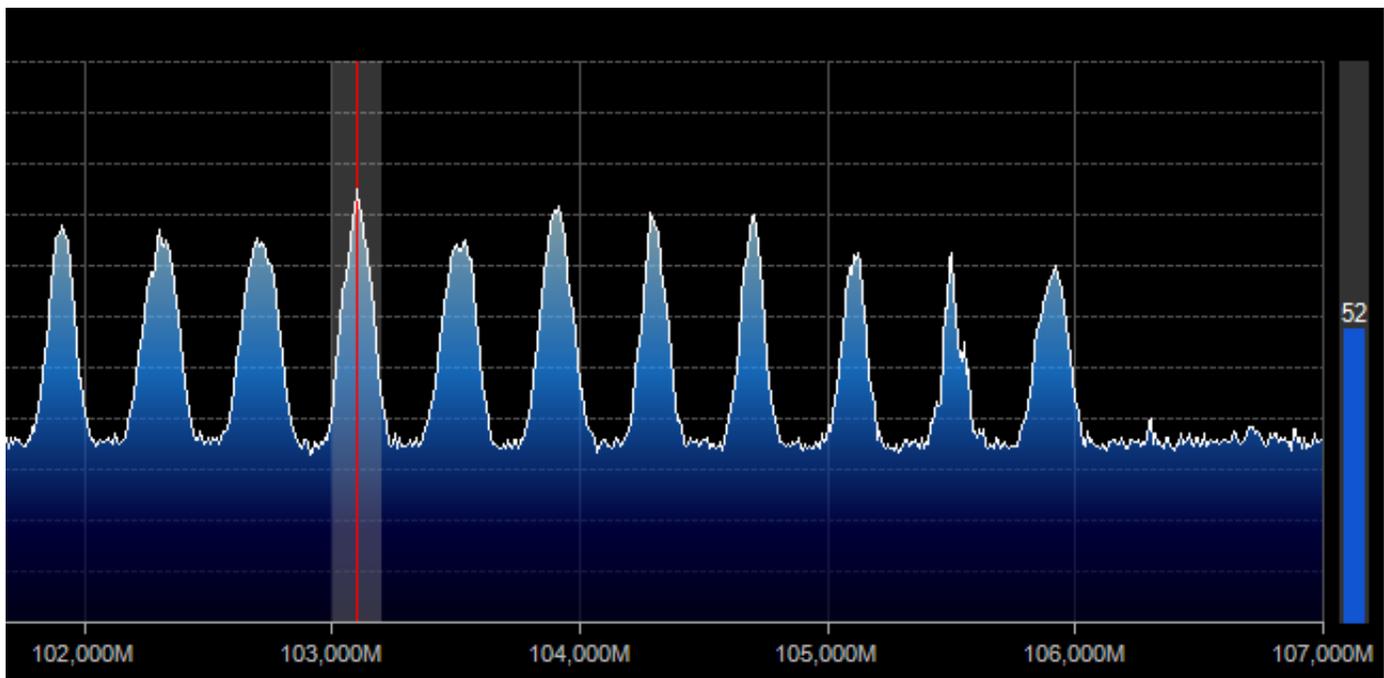
- Sensitivity
- Linearity
- Free (Custom)

The “Linearity” mode is the one you want to start with:



The following fine tuning procedure ensures you have the maximum SNR on the signal of interest \

- Start with the minimum gain
- Increase the gain until the natural noise floor rises by about 5dB
- Check that increasing the gain no longer increase SNR. If not, increase the gain by an extra notch
- Fine tune to maximize the SNR (the blue bar graph on the right)



In any case, you should make sure the RF noise floor just overrides the quantization noise floor of 1

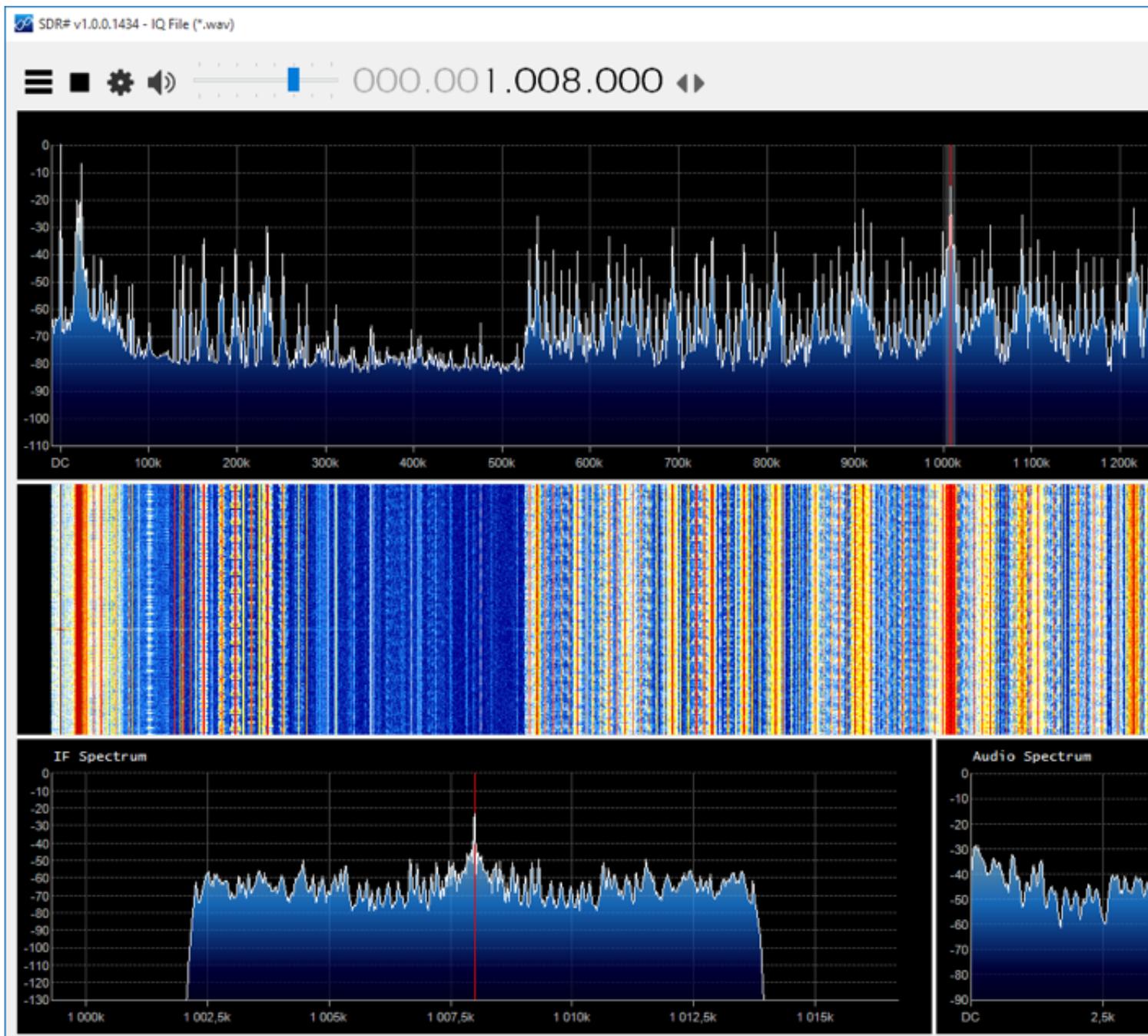
## Using the SpyVerter

Airspy has an option to cover the HF bands: The SpyVerter. It is a low loss, high dynamic range, rugged same kind that is used in very high end HF rigs like the Elecraft K3. It offers HF coverage starting near the L of the Airspy alone. The default software settings allow Airspy to power the SpyVerter via the bias; connect the "IF Output" of the SpyVerter to the RF Input of the Airspy via the supplied barrel adapter.

It is recommended to use the Linearity gain mode in HF.



To verify your setup, plug a HF antenna and tune the AM broadcast band. You should get a view lik



(/downloads/spyverter\_vlf\_lw\_mw.png)

# Using the SPY Server for Remote SDR Operati Presentation

Since revision 1553, we offer a new utility for the Airspy series to convert a Raspberry Pi, an Odroid featured SDR server.

The SPY Server allows you to connect many SDR# "clients" to the same Airspy or RTL-SDR device ov

## How does it work?

When only one client is connected, full control (center frequency, gain) is granted. When there are device and the RF gain are locked.

The default settings allow using the server in the LAN with optimal latency. The "Full IQ" option allows SDR client (SDR#). If the network bandwidth is not sufficient to handle the traffic, uncheck the "Full data and reduced IQ data" that is necessary for decoding one VFO. The bandwidth savings allows us connection.

## Configuration

The SPY Server comes with a standard configuration file that allows you using Airspy or RTL-SDR devices. If you use the same server, you can have multiple configuration files and pass the right one as parameter to the SpyVerter (/products/spyverter-r2) is used, the following parameters should be set in **spyserver**

```
# Initial Center Frequency
#
initial_frequency = 7100000

# Minimum Tunable Frequency
# Comment if using the device default
#
minimum_frequency = 0

# Maximum Tunable Frequency
# Comment if using the device default
#
maximum_frequency = 35000000

# Converter Offset
# Set to -120000000 to enable the SpyVerter offset
converter_offset = -120000000

# Bias-Tee
# For AirspyOne only - Useful for LNA's and SpyVerter
enable_bias_tee = 1
```

## Running on Windows

Edit the configuration file if necessary and double click on **spyserver.exe**.

## Running on x86 Linux

First, make sure you have the latest version of **libairspy** ([https://github.com/airspy/airspyone\\_linux](https://github.com/airspy/airspyone_linux)). Extract "spyserver\_linux\_x86" and "spyserver.config" from the standard zip, chmod and run.

```
$ unzip sdrsharp-86.zip
$ chmod a+x spyspserver_linux_x86
$ ./spyspserver_linux_x86 spyspserver.config
```

## Running on ARM Linux (Raspberry Pi or Odroid)

First, make sure you have the latest version of **libairspy** ([https://github.com/airspy/airspyone\\_linux](https://github.com/airspy/airspyone_linux)). Download and extract the standard ARM package and run.

```
wget http://airspy.com/downloads/spyspserver-arm32.tgz
tar xzf spyspserver-arm32.tgz
./spyspserver spyspserver.config
```

You can also use the **automated** installation script by Rodrigo Pérez which will do everything for you: `wget -qO - http://airspy.com/downloads/install-spyspserver-rpi.sh | sudo bash`

## Linux Troubleshooting

What could go wrong in the Linux world? Well, many things (see the GPL sections 15 and 16 (<https://www.gnu.org/licenses/gpl-3.0.html>)). Here are some of the most obvious ones people reported so far:

- The program runs, but cannot acquire the device: The user mode driver is probably not up to date.
- Sometimes using **sudo** makes things just magically work.
- “GLIBCXX\_3.4.21’ not found” => Try installing GCC 5

## Using the ADSB decoder in embedded ARM boards

### Prerequisite

You need firmware version 1.0 rc7 or newer to use Airspy as an ADSB receiver. Get the latest update from <https://github.com/airspy/firmware/releases> (<https://github.com/airspy/firmware/releases>)

**READ** the instructions before doing anything.

## Raspberry Pi 3 Performance Tuning

The latest Raspbian distros come with a new default CPU governor that is not suitable for sustained high frequency (1200MHz), get very hot, then throttle back to a very low frequency (600 MHz). The two extremes and the USB controller will drop whole packets, which could affect both the number of packets received and the accuracy of the data. The following settings will force the “performance” governor at a much more acceptable CPU frequency.

and without sacrificing the performance of the decodes.

If very high MLAT reliability is required, the following switch should be applied to the decoder:

```
sudo /home/pi/airspy_adsb -l 30005:beast -x -m 12
```

This will run all the decoding in one core using 5 signal phases instead of 10, which requires half of the RAM. Additionally, we recommend to put these lines in **/etc/rc.local** :

```
# /\ RPi3 Only! /\  
echo performance > /sys/devices/system/cpu/cpu0/cpufreq/scaling_governor  
echo performance > /sys/devices/system/cpu/cpu1/cpufreq/scaling_governor  
echo performance > /sys/devices/system/cpu/cpu2/cpufreq/scaling_governor  
echo performance > /sys/devices/system/cpu/cpu3/cpufreq/scaling_governor
```

Then append these lines to **/boot/config.txt** :

```
# /\ RPi3 Only! /\  
force_turbo=1  
arm_freq=800
```

Lastly, you can also disable the “FIQ Fix” that limits the number of USB interrupts. Less USB interrupts reduce the USB hardware with the risk of missing more buffers.

To disable the “FIQ Fix”, you can add the following parameter to the line in **/boot/cmdline.txt** :

```
dwc_otg.fiq_fix_enable=0
```

## Standard setup (non FlightAware)

The whole process for setting up a high performance ADSB receiver has been simplified. For the Raspberry Pi 3, the following commands:

```
mkdir airspy  
cd airspy  
wget http://airspy.com/downloads/airspy_adsb-linux-arm.tgz  
tar xzf airspy_adsb-linux-arm.tgz  
sudo ./airspy_adsb -l 30005:beast -l 47806:asavr -p -m 12 -x &
```

## FlightAware Integration

The easiest way to integrate Airspy into an existing FlightAware PiAware is described here (<https://github.com/dump1090-fa-configuration/44343>).

If you don't need all the details, you can just use this neat installation script by FlightAware member [@mattm](#) images:

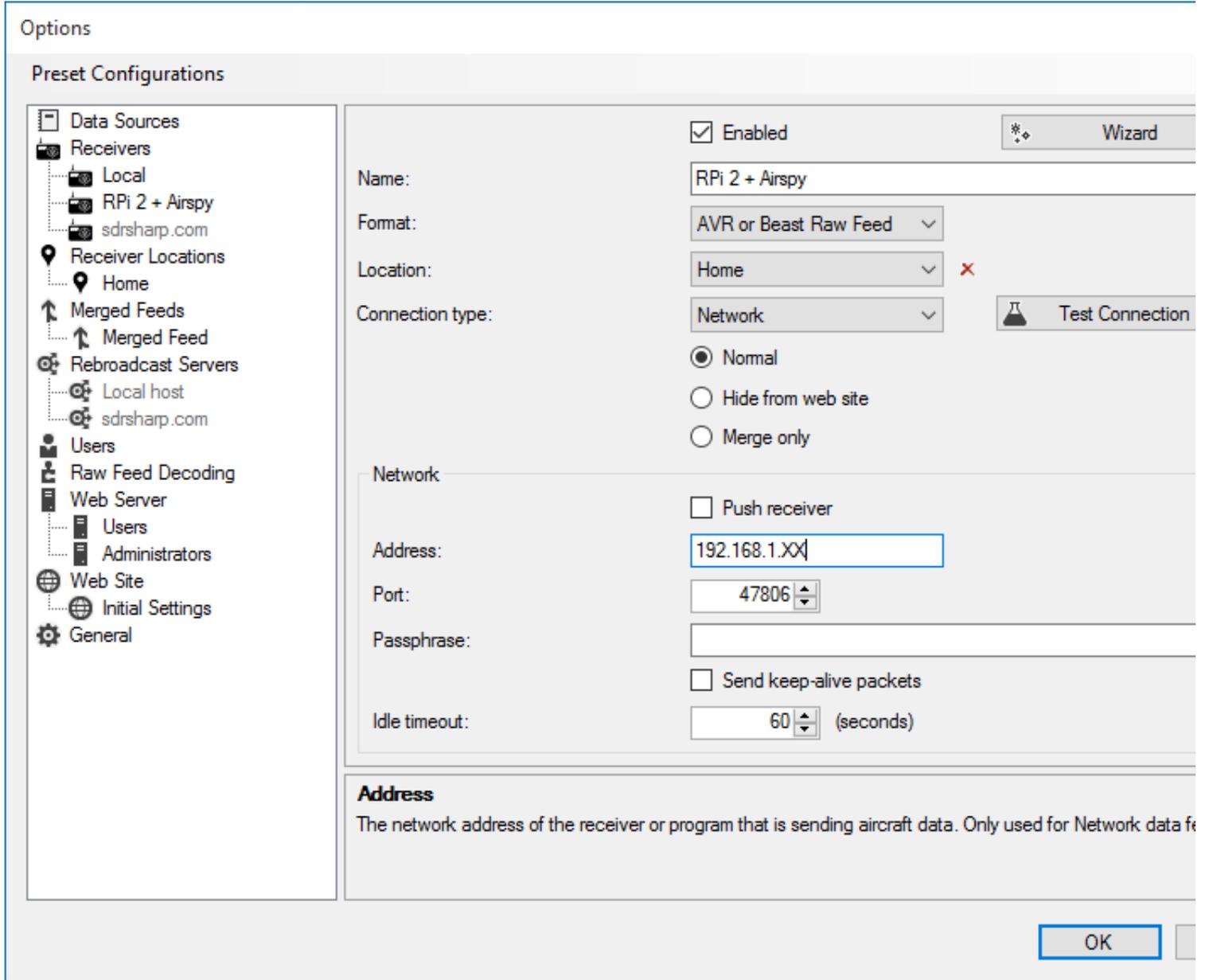
```
sudo bash -c "$(wget -O - https://raw.githubusercontent.com/wiedehopf/airspy-conf/master/install.sh)"
```

# Operation

Once you have your decoder up and running, you can use any aircraft tracking software that supports

## Virtual Radar Server

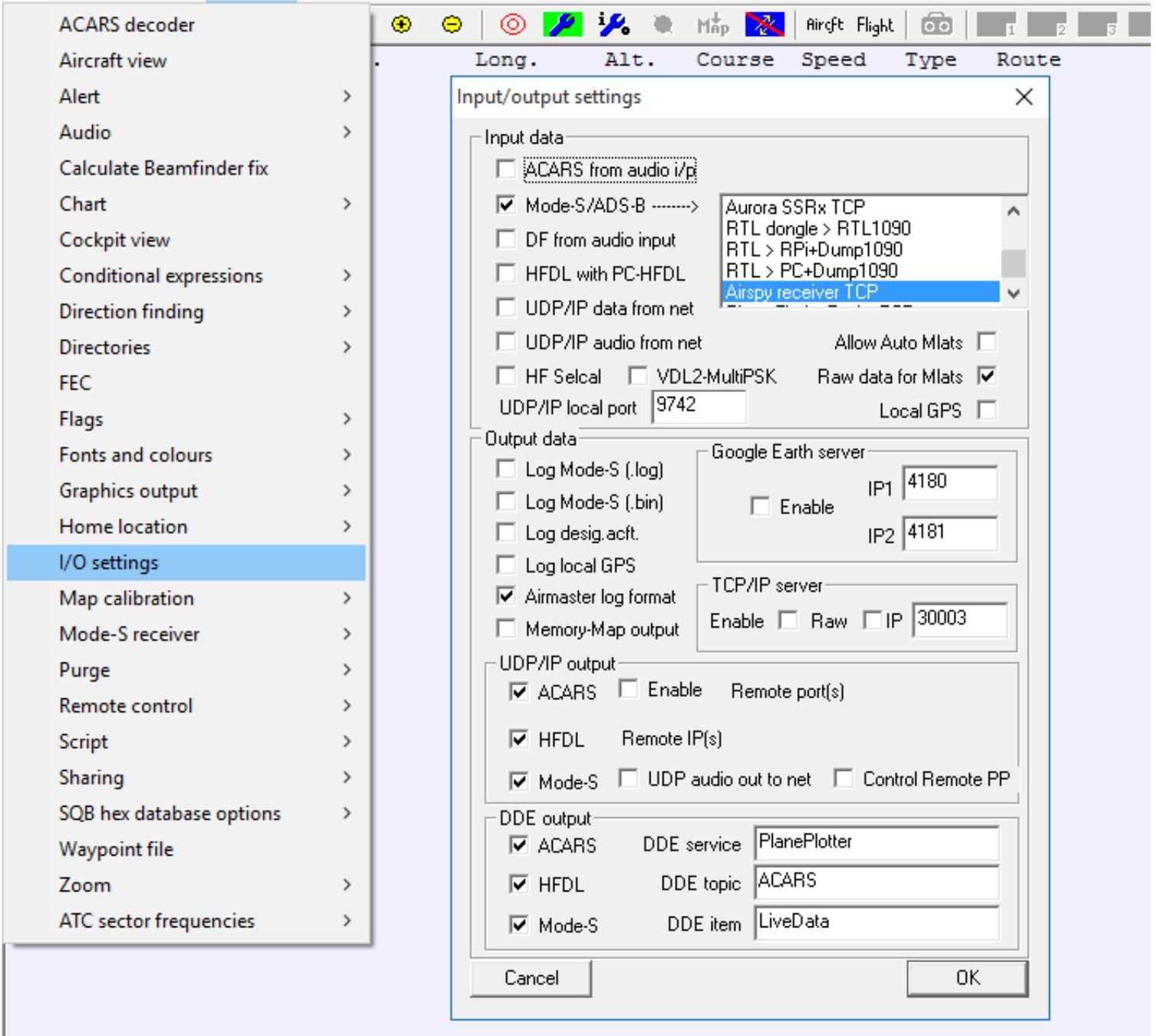
Here's an example configuration for Virtual Radar Server (<http://www.virtualradarserver.co.uk/>):



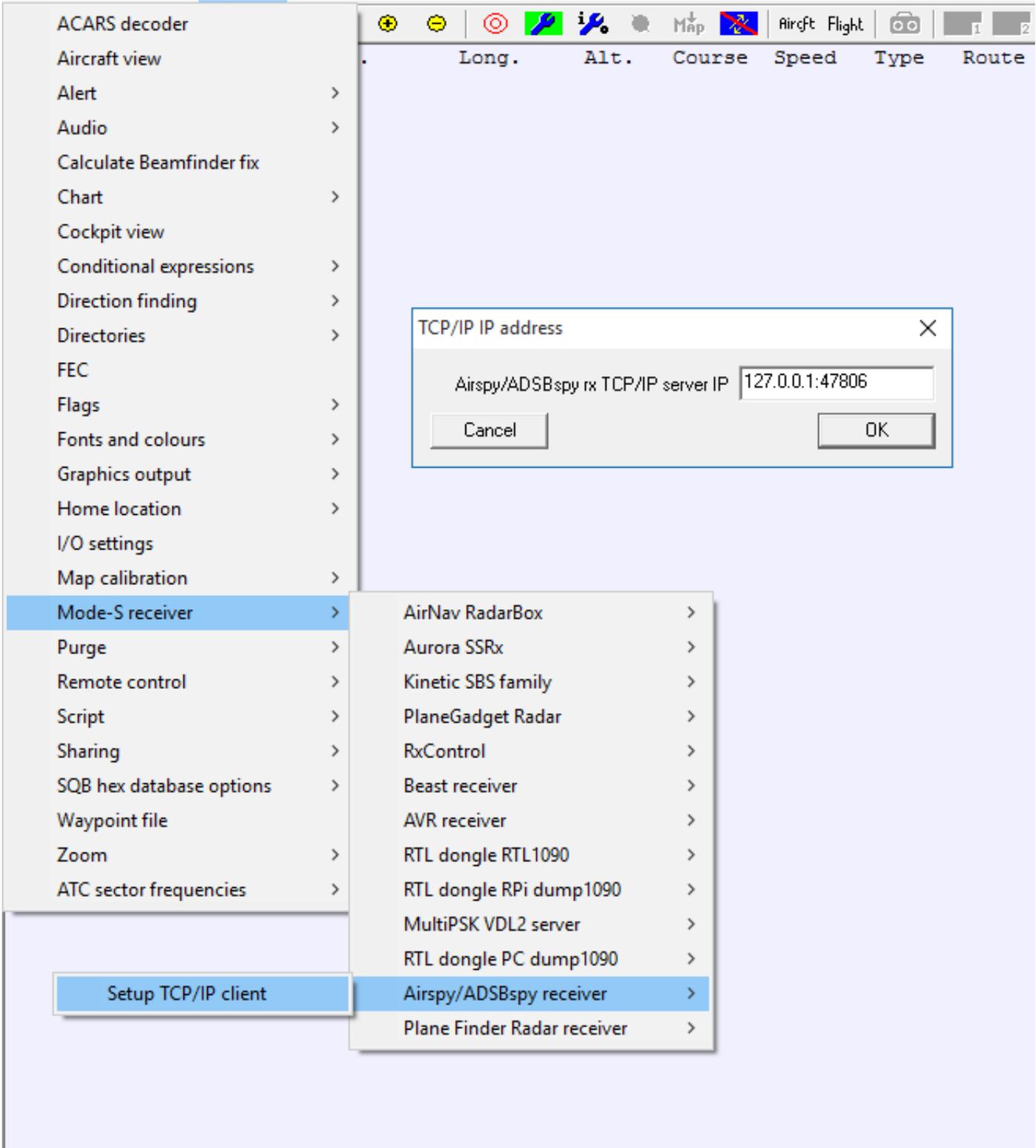
(/downloads/airspy\_pi\_vrs\_config.png)

## Plane Plotter

For Plane Plotter (<http://www.coaa.co.uk/planeplotter.htm>), you can use this configuration:



(/downloads/pp\_config1.png)



(/downloads/pp\_config2.png)

# The effects of oversampling and decimation

The decimation option allows you to trade some of the instantaneous bandwidth to get more bit rate. A rule of thumb is 3dB every time you divide the bandwidth by two. So, decimation by two gives you 3dB more SNR.

To further leverage the effects of the decimation, you can also readjust the gain using the same principle. This gives you more SNR after decimation. So basically, when you use a higher decimation rate, adjust the gain accordingly.

## The Bias-Tee option: 4.5v @ 50mA

In some cases, one may need a very low noise figure. For example, some satellite communication systems require a noise floor of -100dBm/Hz. In such case, using an external preamplifier near the antenna system can improve the overall system noise figure. You can use a preamplifier directly from Airspy by injecting DC at **4.5v**. Of course, such a preamp should have its own power supply and be able to amplify RF signals. The current budget is limited to **50mA**, so that's enough to run most of the modules. Another use case one can imagine is to switch between antennas using that bias signal or even power a small antenna at LF and HF, like the SpyVerter mentioned above.

## Calibration

Starting from June 2016, Airspy R2 units are calibrated in the factory up to ~0.05 PPM. This calibration is stored in the firmware, so upgrading the firmware won't delete it unless you do it by yourself.

The procedure to recalibrate a unit is as follows:

- Open the calibration tool (AirspyCalibrate.exe (/download/)),
- Clear the correction,
- Reset the device (unplug/plug again),
- Inject a known and accurate signal,
- Set its exact frequency in the tool,
- Click on "Calibrate",
- Reset the device.

Note that this procedure requires firmware version 1.0-RC9 (<https://github.com/airspy/firmware/releases>)

## Troubleshooting PC performance problems

We created a set of command line utilities to help troubleshooting the performance problems.

- Download the latest release of the tools package (<https://github.com/airspy/host/releases>)
- Open a console (cmd.exe) and run `airspy_rx -r NUL -t 0`
- Leave it running for 30 seconds, then Ctrl+C
- If the average throughput is below 10.0 MSPS then either your USB controller has problems or you need to optimize your system
  - Use another USB port
  - Update your USB drivers (Prefer OEM drivers to generic ones)
  - Check your anti-virus or any other CPU heavy task

- See also our Wiki: <https://github.com/airspy/host/wiki/Troubleshooting> (<https://github.com/airspy/configuration/solutions>)

## Known issues

- Slow computers won't be able to run Airspy at 10MSPS without dropping samples. That's a lot of modern machine as described in the minimum hardware requirements.
- In a fresh Windows 7/8/10 installation, Windows Update will grab the generic Microsoft USB driver operation and it is advised to update them with the latest version from your OEM. For example, some PCs from choppy to perfectly smooth.
- Some old generation USB 3.0 controllers are not compatible with USB 2.0 devices at high speed. problem. And again, make sure you run Airspy in a modern machine as described in the minimum hardware requirements.
- In some PCs, the experimental 2.5MSPS mode is vulnerable to USB noise. This will be improved in the future. To get lower sample rates is to use some decimation with the 10MSPS stream.
- USB Hubs won't work at the full sampling rate. Just don't use them.
- Beware of overheating. Keep your unit in open air environment while running.

That's all folks!